

General and Differential Topology QR Exam – May 2, 2022

This exam consists of five problems. All manifolds are assumed to be C^∞ . $\mathfrak{X}(M)$ denotes the space of smooth vector fields on the manifold M . All items will be graded independently of each other.

Problem 1. The subgroup Γ of $SU(2)$ generated by the matrix

$$\gamma := \begin{pmatrix} i & 0 \\ 0 & -1 \end{pmatrix} \in SU(2)$$

is isomorphic to \mathbb{Z}_4 , and it acts on the unit three-sphere $S^3 \subset \mathbb{C}^2$ by matrix multiplication. Let $X = S^3/\Gamma$ be the orbit space, with the quotient topology. Answer the following questions, with proofs:

1. Is X second countable?
2. Is X Hausdorff?
3. Is the projection $\pi : S^3 \rightarrow X$ a local homeomorphism?

Problem 2. A smooth $F : M \rightarrow M$ is called a *Lefschetz map* iff for all $p \in M$ such that $F(p) = p$ one has:

$$1 \in \mathbb{R} \text{ is not an eigenvalue of } dF_p : T_pM \rightarrow T_pM.$$

1. Show that F is Lefschetz iff its graph and the diagonal $\Delta \subset M \times M$ intersect transversely.
2. Show that if F is Lefschetz then the set $\{p \in M : F(p) = p\}$ consists of isolated points.
3. Is the converse of the previous statement true?

Problem 3. Let $S^2 \subset \mathbb{R}^3$ be the two-sphere with the standard orientation, and $F : S^2 \rightarrow S^2$ be given by $F(a, b, c) = (a, -b, -c)$. Note that F is a diffeomorphism (no proof needed). Also, let x, y, z denote the restrictions of the coordinate functions to S^2 , and let $\alpha = xydy \wedge dz$.

1. Establish whether or not F is orientation preserving, and compute $F^*(\alpha)$. What does your findings imply about the value of $\int_{S^2} \alpha$? Explain.
2. The vector field $\langle -y, x, 0 \rangle$ in \mathbb{R}^3 is tangent to the sphere, and therefore it restricts to a vector field $X \in \mathfrak{X}(S^2)$. Compute the Lie derivative $\mathcal{L}_X \alpha$.

Problem 4. Let M be a smooth manifold, and $X \in \mathfrak{X}(M \times \mathbb{R})$ be a smooth vector field of the form

$$\forall (p, s) \in M \times \mathbb{R} \quad X_{(p,s)} = (V_{(p,s)}, \partial_s), \quad \text{where } V_{p,s} \in T_p M.$$

(We are identifying $T_{(p,s)}(M \times \mathbb{R})$ with $T_p M \times T_s \mathbb{R}$.) For each $(p, s) \in M \times \mathbb{R}$, let $t \mapsto \Phi_t(p, s)$ be the integral curve of X starting at (p, s) , and denote

$$\phi_{t,s}(p) := \pi(\Phi_{t-s}(p, s)), \quad \text{where } \pi : M \times \mathbb{R} \rightarrow M \text{ is the projection.}$$

1. Show that $\forall t_0 \in \mathbb{R}, p \in M$ the curve on M $t \mapsto \gamma(t) = \phi_{t,t_0}(p)$ is defined in a neighborhood of t_0 and satisfies $\dot{\gamma}(t) = V_{\gamma(t),t}, \gamma(t_0) = p$.
2. Assuming that X is complete, show that $\forall r, s, t \in \mathbb{R}$

$$\phi_{t,s} \circ \phi_{s,r} = \phi_{t,r},$$

where $\phi_{t,s} : M \rightarrow M$ is the map $p \rightarrow \phi_{t,s}(p)$, etc.

Problem 5. Let G be a Lie group with Lie algebra $\mathfrak{g} = T_e G$ (where e is the identity), and let $A, B \in \mathfrak{g}$ be linearly independent elements satisfying $[A, B] = 0$.

1. Carefully explain why $\forall s, t \in \mathbb{R} \exp(sA) \exp(tB) = \exp(tB) \exp(sA)$, where $\exp : \mathfrak{g} \rightarrow G$ is the exponential map.
2. Show that the map $E : \mathbb{R}^2 \ni (s, t) \mapsto \exp(sA) \exp(tB) \in G$ is an immersion.
3. Specialize to the case $G = \mathrm{U}(3)$, and A, B diagonal with diagonal entries the components of $i\vec{\lambda} = \langle i\lambda_1, i\lambda_2, i\lambda_3 \rangle$ and $i\vec{\mu} = \langle i\mu_1, i\mu_2, i\mu_3 \rangle$ respectively.

Under what conditions on $\vec{\lambda}, \vec{\mu} \in \mathbb{R}^3$ is the image of the map E a closed (regular) submanifold of $\mathrm{U}(3)$?